



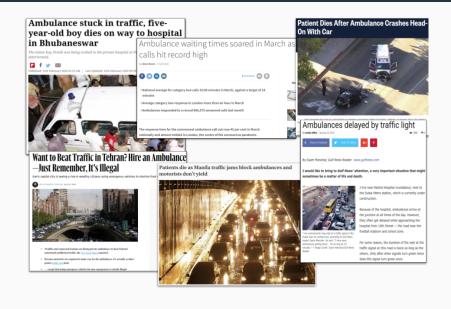
# **Traffic-Light Control for Emergency Vehicles**

Rodrigo Gonçalves de Branco Prof. Edson Norberto Cáceres - Advisor Prof. Ronaldo Alves Ferreira June 26, 2020

College of Computing Federal University of Mato Grosso do Sul - UFMS



# Motivation



# Motivation

# 20 per cent of emergency patient deaths blamed on traffic jam delays

Jan 16. 2017



#### Thailand - 20% of death due to traffic jam - Jan 2017!

#### **Big picture - Mobility and Public Transportation**



#### **Problems and Goals**

#### Reduce the delay (time loss) of the EV in traffic Using traffic light (TL) preemption

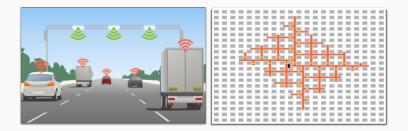


#### Do not impact (too much) other vehicles!

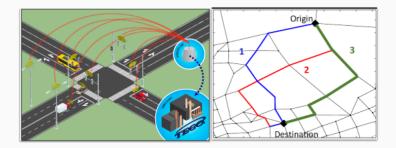


#### **Research challenges**

- Does green light mean vehicles passing through?
- Is it an optimization problem?
- Is it NP-Hard?
- Can we use probabilistic modeling?

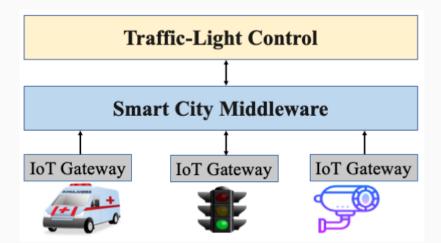


Proximity sensors X Focus on intersection X Unrealistic scenarios X

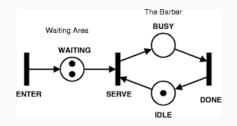


Different EVs, with different routes **X** Hard-to-deploy infrastructure **X** Lack of formal properties of safety for the entire EV route **X** 

#### Focus on solution!!!



# **Proposed Solution - TPN**

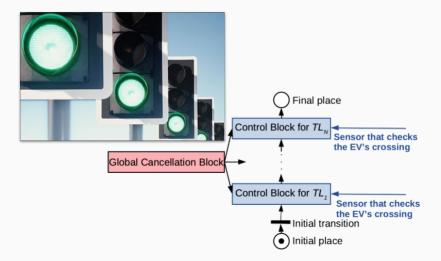


#### **Directed Graph**

- Useful to model distributed, parallel and concurrent systems
- Places, transitions, and directed edges
- Transitions can be fired when tokens are present in their input places
- Timed Petri Net minimum time to fire a transition

## **Proposed Solution - TPN**

#### Control of all TLs in the EV route



## **Proposed Solution - TPN**

#### Individual control of a TL



$$T_{2_{i}} = \begin{cases} 0, \text{if } \frac{d_{TL_{i}}}{ASLpath_{i}} \leq \epsilon \text{ or } ASpath_{i} \leq \delta \\ \max\{(\frac{d_{TL_{i}}}{ASLpath_{i}} - t_{flush_{i}}) \times (1 - Opath_{i}), 0\} \end{cases}$$
(1)

### Why is it safe?

- i It executes at most one preemption action
- ii It does not restore the state of any  $TL_i$  before its preemption
- iii It executes at most one restore action

The token that gets to  $P_3$  arrives only via  $P_0$ , which receives a token only once from the *Initial Transition* for  $TL_1$  or from  $T_1$  of  $TL_{i-1}$  for all  $TL_i$ ,  $2 \le i \le N$ . Because the preemption action happens when the token gets to  $P_3$ , a control block executes at most one preemption.

For properties (*ii*) and (*iii*), the token must get to  $P_6$  via  $T_4$ . As  $T_4$  depends on  $P_4$  and  $P_3$ , a control block does not restore the state of a  $TL_i$  before  $P_3$  triggered the preemption. Likewise, because  $P_4$  gets only one token, the restore action happens at most once.

# **Performance Evaluation**



- SUMO Simulator
- SP and NY
- All routes were generated using the OSMWebWizard tool
- Cars, trucks and motorcycles

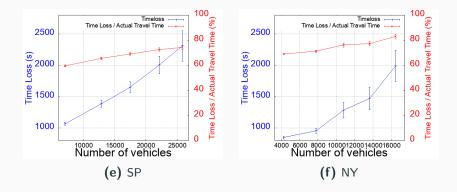
# **Performance Evaluation**

a long took
E Trans Constant
A Material In and Andrews
A Explan
Printing Income Tests France
E Lobar Salar
A BRA

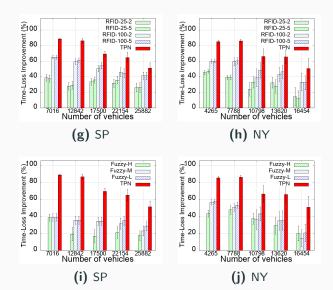
Scenario	Car	Truck	Moto	Total	Scenario	Car	Truck	Moto	Total
1	3494	1167	2355	7016	1	2128	706	1431	4265
2	5826	2322	4694	12842	2	3544	1412	2833	7789
3	8136	3509	5855	17500	3	5009	2151	3639	10799
4	10457	4656	7041	22154	4	6422	2847	4353	13622
5	12258	5624	8000	25882	5	7830	3579	5045	16454
(a) Sao Paulo				(b) New York					

- A vehicle was chosen to be the EV in each city (crossing 65 TLs)
- Routes
  - EV: fixed
  - Other: dynamic
- Two other algorithms: RFID and Fuzzy
- 60 independent simulation runs

#### Simulation Results - Time Loss - No Preemption



# Simulation Results - Time Loss Improvement - TPN $\times$ RFID And Fuzzy



16

# Limitations and Future Work



- Use more than one EV (conflict policies)
- $\bullet\,$  Allow improvement beyond 100%
  - by allowing that the EV speed be greater than the maximum speed limit of the streets
- Integrate our solution with the InterSCity middleware
  - real versus simulated time
- Go deep on Research challenges

# **Final Considerations**

- Source code at https://github.com/ smartcity-tpn-preemption/tpn-preemption
- Comparision example
  - SP-1 https://youtu.be/\_AgZ3HyDgCs
  - SP-5 https://youtu.be/7r\_lyiemsE0

My e-mail: rodrigo.g.branco@gmail.com

